

Strongly Minimal Sets in Continuous Logic

James Hanson

University of Wisconsin-Madison

August 13, 2020
Online Logic Seminar

Continuous Logic

- Generalization of first-order logic for *metric structures*: Complete bounded metric spaces with bounded uniformly continuous \mathbb{R} -valued predicates and uniformly continuous functions.

Continuous Logic

- Generalization of first-order logic for *metric structures*: Complete bounded metric spaces with bounded uniformly continuous \mathbb{R} -valued predicates and uniformly continuous functions.
- These restrictions can be motivated by compatibility with ultraproducts.

Continuous Logic

- Generalization of first-order logic for *metric structures*: Complete bounded metric spaces with bounded uniformly continuous \mathbb{R} -valued predicates and uniformly continuous functions.
- These restrictions can be motivated by compatibility with ultraproducts.
- Formulas are real valued with sup and inf as quantifiers and arbitrary continuous functions $F : \mathbb{R}^k \rightarrow \mathbb{R}$ for $k \leq \omega$ as connectives.

Continuous Logic

- Generalization of first-order logic for *metric structures*: Complete bounded metric spaces with bounded uniformly continuous \mathbb{R} -valued predicates and uniformly continuous functions.
- These restrictions can be motivated by compatibility with ultraproducts.
- Formulas are real valued with sup and inf as quantifiers and arbitrary continuous functions $F : \mathbb{R}^k \rightarrow \mathbb{R}$ for $k \leq \omega$ as connectives.
- Formulas are closed under uniform limits up to logical equivalence.

Continuous Logic

- Generalization of first-order logic for *metric structures*: Complete bounded metric spaces with bounded uniformly continuous \mathbb{R} -valued predicates and uniformly continuous functions.
- These restrictions can be motivated by compatibility with ultraproducts.
- Formulas are real valued with sup and inf as quantifiers and arbitrary continuous functions $F : \mathbb{R}^k \rightarrow \mathbb{R}$ for $k \leq \omega$ as connectives.
- Formulas are closed under uniform limits up to logical equivalence.
- Formulas are uniformly continuous on metric structures.

Continuous Logic

- Generalization of first-order logic for *metric structures*: Complete bounded metric spaces with bounded uniformly continuous \mathbb{R} -valued predicates and uniformly continuous functions.
- These restrictions can be motivated by compatibility with ultraproducts.
- Formulas are real valued with sup and inf as quantifiers and arbitrary continuous functions $F : \mathbb{R}^k \rightarrow \mathbb{R}$ for $k \leq \omega$ as connectives.
- Formulas are closed under uniform limits up to logical equivalence.
- Formulas are uniformly continuous on metric structures.
- *Zeroset* of a formula is the set of all tuples where it evaluates to 0. (Also refers to corresponding set of types.)

Continuous Logic

- Generalization of first-order logic for *metric structures*: Complete bounded metric spaces with bounded uniformly continuous \mathbb{R} -valued predicates and uniformly continuous functions.
- These restrictions can be motivated by compatibility with ultraproducts.
- Formulas are real valued with sup and inf as quantifiers and arbitrary continuous functions $F : \mathbb{R}^k \rightarrow \mathbb{R}$ for $k \leq \omega$ as connectives.
- Formulas are closed under uniform limits up to logical equivalence.
- Formulas are uniformly continuous on metric structures.
- *Zeroset* of a formula is the set of all tuples where it evaluates to 0. (Also refers to corresponding set of types.)
- In discrete logic zerosets correspond to countably type-definable sets.

Continuous Logic

- Generalization of first-order logic for *metric structures*: Complete bounded metric spaces with bounded uniformly continuous \mathbb{R} -valued predicates and uniformly continuous functions.
- These restrictions can be motivated by compatibility with ultraproducts.
- Formulas are real valued with sup and inf as quantifiers and arbitrary continuous functions $F : \mathbb{R}^k \rightarrow \mathbb{R}$ for $k \leq \omega$ as connectives.
- Formulas are closed under uniform limits up to logical equivalence.
- Formulas are uniformly continuous on metric structures.
- *Zeroset* of a formula is the set of all tuples where it evaluates to 0. (Also refers to corresponding set of types.)
- In discrete logic zerosets correspond to countably type-definable sets.
- A zeroset is *definable* if there is a formula that is the distance to it in any model (relative quantification).

Type Spaces in Continuous Logic

The set of types in a theory T in the variable tuple \bar{x} is written $S_{\bar{x}}(T)$ or $S_n(T)$.

Type Spaces in Continuous Logic

The set of types in a theory T in the variable tuple \bar{x} is written $S_{\bar{x}}(T)$ or $S_n(T)$.

- Points (called *types*) are maximal consistent sets of real values for formulas. Topology is the coarsest that makes all formulas continuous.

Type Spaces in Continuous Logic

The set of types in a theory T in the variable tuple \bar{x} is written $S_{\bar{x}}(T)$ or $S_n(T)$.

- Points (called *types*) are maximal consistent sets of real values for formulas. Topology is the coarsest that makes all formulas continuous.
- $S_n(T)$ is compact and Hausdorff.

Type Spaces in Continuous Logic

The set of types in a theory T in the variable tuple \bar{x} is written $S_{\bar{x}}(T)$ or $S_n(T)$.

- Points (called *types*) are maximal consistent sets of real values for formulas. Topology is the coarsest that makes all formulas continuous.
- $S_n(T)$ is compact and Hausdorff.
- $S_n(T)$ may fail to be zero-dimensional.

Type Spaces in Continuous Logic

The set of types in a theory T in the variable tuple \bar{x} is written $S_{\bar{x}}(T)$ or $S_n(T)$.

- Points (called *types*) are maximal consistent sets of real values for formulas. Topology is the coarsest that makes all formulas continuous.
- $S_n(T)$ is compact and Hausdorff.
- $S_n(T)$ may fail to be zero-dimensional.
- Continuous function $S_n(T) \rightarrow \mathbb{R}$ correspond precisely to formulas with free variables among \bar{x} (modulo T).

Strongly Minimal Sets

A zeroset is *algebraic* if it has a compact set of realizations in any model.

Strongly Minimal Sets

A zeroset is *algebraic* if it has a compact set of realizations in any model.

Definition

A *strongly minimal set* is a definable set with no pair of disjoint non-algebraic zerosets over any parameters.

Strongly Minimal Sets

A zeroset is *algebraic* if it has a compact set of realizations in any model.

Definition

A *strongly minimal set* is a definable set with no pair of disjoint non-algebraic zerosets over any parameters.

- Has a unique non-algebraic type over any parameters. Such types are also called *strongly minimal*.

Strongly Minimal Sets

A zeroset is *algebraic* if it has a compact set of realizations in any model.

Definition

A *strongly minimal set* is a definable set with no pair of disjoint non-algebraic zerosets over any parameters.

- Has a unique non-algebraic type over any parameters. Such types are also called *strongly minimal*.
- A theory is *strongly minimal* if $[d(x, x) = 0]$ is a strongly minimal set.

Strongly Minimal Sets

A zeroset is *algebraic* if it has a compact set of realizations in any model.

Definition

A *strongly minimal set* is a definable set with no pair of disjoint non-algebraic zerosets over any parameters.

- Has a unique non-algebraic type over any parameters. Such types are also called *strongly minimal*.
- A theory is *strongly minimal* if $[d(x, x) = 0]$ is a strongly minimal set.
- Much of the internal machinery of strongly minimal sets goes through in continuous logic (e.g. pregeometry generated by acl), but...

Strongly Minimal Sets

A zeroset is *algebraic* if it has a compact set of realizations in any model.

Definition

A *strongly minimal set* is a definable set with no pair of disjoint non-algebraic zerosets over any parameters.

- Has a unique non-algebraic type over any parameters. Such types are also called *strongly minimal*.
- A theory is *strongly minimal* if $[d(x, x) = 0]$ is a strongly minimal set.
- Much of the internal machinery of strongly minimal sets goes through in continuous logic (e.g. pregeometry generated by acl), but...
- ...they do not play the same role in uncountably categorical theories:

Strongly Minimal Sets

A zeroset is *algebraic* if it has a compact set of realizations in any model.

Definition

A *strongly minimal set* is a definable set with no pair of disjoint non-algebraic zerosets over any parameters.

- Has a unique non-algebraic type over any parameters. Such types are also called *strongly minimal*.
- A theory is *strongly minimal* if $[d(x, x) = 0]$ is a strongly minimal set.
- Much of the internal machinery of strongly minimal sets goes through in continuous logic (e.g. pregeometry generated by acl), but...
- ...they do not play the same role in uncountably categorical theories:
 - Some do not have any strongly minimal sets (e.g. ∞ -dim. Hilbert space).

Strongly Minimal Sets

A zeroset is *algebraic* if it has a compact set of realizations in any model.

Definition

A *strongly minimal set* is a definable set with no pair of disjoint non-algebraic zerosets over any parameters.

- Has a unique non-algebraic type over any parameters. Such types are also called *strongly minimal*.
- A theory is *strongly minimal* if $[d(x, x) = 0]$ is a strongly minimal set.
- Much of the internal machinery of strongly minimal sets goes through in continuous logic (e.g. pregeometry generated by acl), but...
- ...they do not play the same role in uncountably categorical theories:
 - Some do not have any strongly minimal sets (e.g. ∞ -dim. Hilbert space).
 - Even when they do, they may only show up in imaginaries or over high dimensional models. (H.)

An Important Fact about Strongly Minimal Sets

Fact

Let T be a strongly minimal theory.

An Important Fact about Strongly Minimal Sets

Fact

Let T be a strongly minimal theory. Models of T are (uniformly) locally compact.

An Important Fact about Strongly Minimal Sets

Fact

Let T be a strongly minimal theory. Models of T are (uniformly) locally compact.

Corollaries:

- There is an $\varepsilon > 0$ such that if $d(a, b) < \varepsilon$, then $b \in \text{acl}(a)$.

An Important Fact about Strongly Minimal Sets

Fact

Let T be a strongly minimal theory. Models of T are (uniformly) locally compact.

Corollaries:

- There is an $\varepsilon > 0$ such that if $d(a, b) < \varepsilon$, then $b \in \text{acl}(a)$.
- For any $a, b \in M$, if b is in the connected component of a , then $b \in \text{acl}(a)$.

An Important Fact about Strongly Minimal Sets

Fact

Let T be a strongly minimal theory. Models of T are (uniformly) locally compact.

Corollaries:

- There is an $\varepsilon > 0$ such that if $d(a, b) < \varepsilon$, then $b \in \text{acl}(a)$.
- For any $a, b \in M$, if b is in the connected component of a , then $b \in \text{acl}(a)$.
- If $M \prec N$ are models of T , then M is an open subset of N .

An Important Fact about Strongly Minimal Sets

Fact

Let T be a strongly minimal theory. Models of T are (uniformly) locally compact.

Corollaries:

- There is an $\varepsilon > 0$ such that if $d(a, b) < \varepsilon$, then $b \in \text{acl}(a)$.
- For any $a, b \in M$, if b is in the connected component of a , then $b \in \text{acl}(a)$.
- If $M \prec N$ are models of T , then M is an open subset of N .

Strongly minimal theories behave a lot more like discrete theories than arbitrary continuous theories do.

Anything New?

Noquez asked in her thesis whether or not there are any strongly minimal sets that are not in some sense just discrete.

Anything New?

Noquez asked in her thesis whether or not there are any strongly minimal sets that are not in some sense just discrete.

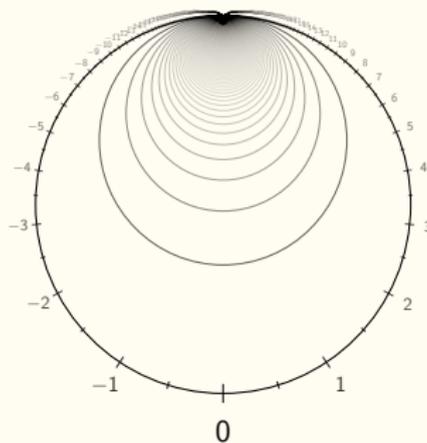
Definition

A theory T is *essentially continuous* if it does not interpret any infinite discrete structure.

An Old Strongly Minimal Set

Proposition

The theory T of $(\mathbb{R}, +)$ with the metric $\min\{|x - y|, 1\}$ is strongly minimal and essentially continuous.

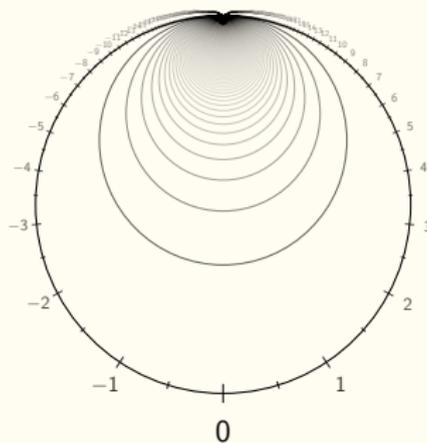


$S_1(M)$ of $M \succ \mathbb{R}$

An Old Strongly Minimal Set

Proposition

The theory T of $(\mathbb{R}, +)$ with the metric $\min\{|x - y|, 1\}$ is strongly minimal and essentially continuous.



$S_1(M)$ of $M \succ \mathbb{R}$

Strong Minimality Proof.

Argue that models of T are of the form $\mathbb{R} \oplus \mathbb{Q}^{\kappa}$ and show that all elements realizing a non-algebraic type over some set of parameters are automorphic. □

Essential Continuity Proof I

- Let H be the home sort.

Essential Continuity Proof I

- Let H be the home sort.
- Assume that T has an infinite discrete imaginary sort.

Essential Continuity Proof I

- Let H be the home sort.
- Assume that T has an infinite discrete imaginary sort.
- By ω -stability there is a discrete strongly minimal set, D , in that sort.

Essential Continuity Proof I

- Let H be the home sort.
- Assume that T has an infinite discrete imaginary sort.
- By ω -stability there is a discrete strongly minimal set, D , in that sort.
- There must be a compact-to-compact correspondence, R , between H and D .

Essential Continuity Proof I

- Let H be the home sort.
- Assume that T has an infinite discrete imaginary sort.
- By ω -stability there is a discrete strongly minimal set, D , in that sort.
- There must be a compact-to-compact correspondence, R , between H and D . Since D is discrete, this is actually a compact-to-finite correspondence.

Essential Continuity Proof II

Essential Continuity Proof II

- What this means precisely is that R is the zeroset of some formula $\varphi(x:H, y:D)$.

Essential Continuity Proof II

- What this means precisely is that R is the zeroset of some formula $\varphi(x:H, y:D)$.
- For generic $a \in H$, there is some fixed $\varepsilon > 0$ such that if $\varphi(a, b) \neq 0$, then $\varphi(a, b) > \varepsilon$.

Essential Continuity Proof II

- What this means precisely is that R is the zeroset of some formula $\varphi(x:H, y:D)$.
- For generic $a \in H$, there is some fixed $\varepsilon > 0$ such that if $\varphi(a, b) \neq 0$, then $\varphi(a, b) > \varepsilon$.
- But, by uniform continuity of $\varphi(x, y)$, this implies that if $\varphi(a, c) = 0$, then $\varphi(a + r, c) = 0$ for all $r \in \mathbb{R}$.

Essential Continuity Proof II

- What this means precisely is that R is the zeroset of some formula $\varphi(x:H, y:D)$.
- For generic $a \in H$, there is some fixed $\varepsilon > 0$ such that if $\varphi(a, b) \neq 0$, then $\varphi(a, b) > \varepsilon$.
- But, by uniform continuity of $\varphi(x, y)$, this implies that if $\varphi(a, c) = 0$, then $\varphi(a + r, c) = 0$ for all $r \in \mathbb{R}$. Contradiction. \square

Generalizing

In the proof of essential continuity we did not use anything about $(\mathbb{R}, +)$ other than the fact that generic elements have non-compact connected components, hence:

In the proof of essential continuity we did not use anything about $(\mathbb{R}, +)$ other than the fact that generic elements have non-compact connected components, hence:

Proposition

If T is a strongly minimal theory whose generic elements have non-compact connected components, then T is essentially continuous.

In the proof of essential continuity we did not use anything about $(\mathbb{R}, +)$ other than the fact that generic elements have non-compact connected components, hence:

Proposition

If T is a strongly minimal theory whose generic elements have non-compact connected components, then T is essentially continuous.

Converse?

Connectivity

- Problem: Continuous logic cannot talk about connectivity directly.

Connectivity

- Problem: Continuous logic cannot talk about connectivity directly.
- Can talk about ' ε -connectivity' (to the same extent that discrete logic can talk about graph connectivity).

Connectivity

- Problem: Continuous logic cannot talk about connectivity directly.
- Can talk about ' ε -connectivity' (to the same extent that discrete logic can talk about graph connectivity).



Definition

Let \sim_ε be the transitive closure of the relation $d(x, y) < \varepsilon$. Let $[a]_\varepsilon$ be the \sim_ε -equivalence class of a .

Connectivity

- Problem: Continuous logic cannot talk about connectivity directly.
- Can talk about ' ε -connectivity' (to the same extent that discrete logic can talk about graph connectivity).



Definition

Let \sim_ε be the transitive closure of the relation $d(x, y) < \varepsilon$. Let $[a]_\varepsilon$ be the \sim_ε -equivalence class of a .

- If a and b are in the same connected component of X , then $a \sim_\varepsilon b$ for every $\varepsilon > 0$. (Converse can fail.)

Connectivity

- Problem: Continuous logic cannot talk about connectivity directly.
- Can talk about ' ε -connectivity' (to the same extent that discrete logic can talk about graph connectivity).



Definition

Let \sim_ε be the transitive closure of the relation $d(x, y) < \varepsilon$. Let $[a]_\varepsilon$ be the \sim_ε -equivalence class of a .

- If a and b are in the same connected component of X , then $a \sim_\varepsilon b$ for every $\varepsilon > 0$. (Converse can fail.)
- $x \sim_\varepsilon y$ is an 'open formula' (co-zeroset).

Converse I

Let T be a strongly minimal theory and assume that generic elements in T have compact connected components.

Converse I

Let T be a strongly minimal theory and assume that generic elements in T have compact connected components.

- Let a be a generic element. By local compactness, there is a compact clopen set Q containing a .

Converse I

Let T be a strongly minimal theory and assume that generic elements in T have compact connected components.

- Let a be a generic element. By local compactness, there is a compact clopen set Q containing a .
- Find $\varepsilon > 0$ small enough that Q and its complement are $> \varepsilon$ apart (exists by local compactness) and that $d(a, b) < \varepsilon \Rightarrow b \in \text{acl}(a)$.

Converse I

Let T be a strongly minimal theory and assume that generic elements in T have compact connected components.

- Let a be a generic element. By local compactness, there is a compact clopen set Q containing a .
- Find $\varepsilon > 0$ small enough that Q and its complement are $> \varepsilon$ apart (exists by local compactness) and that $d(a, b) < \varepsilon \Rightarrow b \in \text{acl}(a)$.
- $[a]_\varepsilon$ must be a clopen subset of Q and is therefore compact.

Converse I

Let T be a strongly minimal theory and assume that generic elements in T have compact connected components.

- Let a be a generic element. By local compactness, there is a compact clopen set Q containing a .
- Find $\varepsilon > 0$ small enough that Q and its complement are $> \varepsilon$ apart (exists by local compactness) and that $d(a, b) < \varepsilon \Rightarrow b \in \text{acl}(a)$.
- $[a]_\varepsilon$ must be a clopen subset of Q and is therefore compact. So \sim_ε is witnessed by chains of uniformly bounded length for generics.

Converse II

By compactness there is some $0 < \delta < \varepsilon$ such that \sim_ε is implied by \sim_δ for generic elements, with witnessing chains of the same length.

By compactness there is some $0 < \delta < \varepsilon$ such that \sim_ε is implied by \sim_δ for generic elements, with witnessing chains of the same length. Consider this formula for n larger than the bound:

$$\rho_n(z_0, z_n) := \inf_{z_1 \dots z_{n-1}} \max_{i < n} \max\{0, d(z_i, z_{i+1}) - \delta\}$$

Converse II

By compactness there is some $0 < \delta < \varepsilon$ such that \sim_ε is implied by \sim_δ for generic elements, with witnessing chains of the same length. Consider this formula for n larger than the bound:

$$\rho_n(z_0, z_n) := \inf_{z_1 \dots z_{n-1}} \max_{i < n} \max\{0, d(z_i, z_{i+1}) - \delta\}$$

We have established that for generic a and arbitrary b ,

Converse II

By compactness there is some $0 < \delta < \varepsilon$ such that \sim_ε is implied by \sim_δ for generic elements, with witnessing chains of the same length. Consider this formula for n larger than the bound:

$$\rho_n(z_0, z_n) := \inf_{z_1 \dots z_{n-1}} \max_{i < n} \max\{0, d(z_i, z_{i+1}) - \delta\}$$

We have established that for generic a and arbitrary b ,

- if $a \sim_\varepsilon b$, then $\rho_n(a, b) = 0$ and

Converse II

By compactness there is some $0 < \delta < \varepsilon$ such that \sim_ε is implied by \sim_δ for generic elements, with witnessing chains of the same length. Consider this formula for n larger than the bound:

$$\rho_n(z_0, z_n) := \inf_{z_1 \dots z_{n-1}} \max_{i < n} \max\{0, d(z_i, z_{i+1}) - \delta\}$$

We have established that for generic a and arbitrary b ,

- if $a \sim_\varepsilon b$, then $\rho_n(a, b) = 0$ and
- if $a \not\sim_\varepsilon b$, then $\rho_n(a, b) \geq \varepsilon - \delta$.

The generic type $p(x)$ satisfies the 'formula'

$$U(x) := \forall y \left(\rho_n(x, y) < \frac{1}{3}(\varepsilon - \delta) \right) \vee \left(\rho_n(x, y) > \frac{2}{3}(\varepsilon - \delta) \right),$$

Converse III

The generic type $p(x)$ satisfies the 'formula'

$$U(x) := \forall y \left(\rho_n(x, y) < \frac{1}{3}(\varepsilon - \delta) \right) \vee \left(\rho_n(x, y) > \frac{2}{3}(\varepsilon - \delta) \right),$$

which corresponds* to an open neighborhood of p ,

Converse III

The generic type $p(x)$ satisfies the 'formula'

$$U(x) := \forall y \left(\rho_n(x, y) < \frac{1}{3}(\varepsilon - \delta) \right) \vee \left(\rho_n(x, y) > \frac{2}{3}(\varepsilon - \delta) \right),$$

which corresponds* to an open neighborhood of p , and so in particular is satisfied by all but an algebraic set of types.

Converse III

The generic type $p(x)$ satisfies the 'formula'

$$U(x) := \forall y \left(\rho_n(x, y) < \frac{1}{3}(\varepsilon - \delta) \right) \vee \left(\rho_n(x, y) > \frac{2}{3}(\varepsilon - \delta) \right),$$

which corresponds* to an open neighborhood of p , and so in particular is satisfied by all but an algebraic set of types. The set of elements satisfying $\neg U(x)$ are closed under \sim_ε as well,* so they too have a uniform bound m on witnessing chain lengths for \sim_ε .

Converse III

The generic type $p(x)$ satisfies the 'formula'

$$U(x) := \forall y \left(\rho_n(x, y) < \frac{1}{3}(\varepsilon - \delta) \right) \vee \left(\rho_n(x, y) > \frac{2}{3}(\varepsilon - \delta) \right),$$

which corresponds* to an open neighborhood of p , and so in particular is satisfied by all but an algebraic set of types. The set of elements satisfying $\neg U(x)$ are closed under \sim_ε as well,* so they too have a uniform bound m on witnessing chain lengths for \sim_ε .

So the formula

$$\min \left\{ 1, \frac{3}{2(\varepsilon - \delta)} \rho_{n+m+1}(x, y) \right\}$$

is $\{0, 1\}$ -valued and defines $\sim_{\frac{\varepsilon+\delta}{2}}$. The quotient is discrete and strongly minimal. □

Full Statement

We have also shown that if the connected components of generic elements are compact then arbitrary connected components are compact.

Full Statement

We have also shown that if the connected components of generic elements are compact then arbitrary connected components are compact.

Theorem (H.)

Let T be a strongly minimal theory. TFAE:

We have also shown that if the connected components of generic elements are compact then arbitrary connected components are compact.

Theorem (H.)

Let T be a strongly minimal theory. TFAE:

- T is essentially continuous.

We have also shown that if the connected components of generic elements are compact then arbitrary connected components are compact.

Theorem (H.)

Let T be a strongly minimal theory. TFAE:

- T is essentially continuous.
- Some model has a non-compact connected component.

We have also shown that if the connected components of generic elements are compact then arbitrary connected components are compact.

Theorem (H.)

Let T be a strongly minimal theory. TFAE:

- T is essentially continuous.
- Some model has a non-compact connected component.
- Every generic element has a non-compact connected component.

We have also shown that if the connected components of generic elements are compact then arbitrary connected components are compact.

Theorem (H.)

Let T be a strongly minimal theory. TFAE:

- T is essentially continuous.
- Some model has a non-compact connected component.
- Every generic element has a non-compact connected component.
- T does not have a \emptyset -definable infinite discrete quotient.

Full Statement

We have also shown that if the connected components of generic elements are compact then arbitrary connected components are compact.

Theorem (H.)

Let T be a strongly minimal theory. TFAE:

- T is essentially continuous.
- Some model has a non-compact connected component.
- Every generic element has a non-compact connected component.
- T does not have a \emptyset -definable infinite discrete quotient.

What about the prime model?

What about the Prime Model?

The prime model may fail to have a non-compact connected component.

What about the Prime Model?

The prime model may fail to have a non-compact connected component.

Counterexample

The set $\{\pm \log n : n \geq 1\}$ as a subspace of \mathbb{R} with the metric $\min\{|x - y|, 1\}$ is essentially continuous strongly minimal but has a totally disconnected prime model.

What about the Prime Model?

The prime model may fail to have a non-compact connected component.

Counterexample

The set $\{\pm \log n : n \geq 1\}$ as a subspace of \mathbb{R} with the metric $\min\{|x - y|, 1\}$ is essentially continuous strongly minimal but has a totally disconnected prime model.

Proof.

The relevant set is actually definable in $(\mathbb{R}, 0)$, and so this is the theory of a non-compact definable subset of a strongly minimal set and so is also strongly minimal.

What about the Prime Model?

The prime model may fail to have a non-compact connected component.

Counterexample

The set $\{\pm \log n : n \geq 1\}$ as a subspace of \mathbb{R} with the metric $\min\{|x - y|, 1\}$ is essentially continuous strongly minimal but has a totally disconnected prime model.

Proof.

The relevant set is actually definable in $(\mathbb{R}, 0)$, and so this is the theory of a non-compact definable subset of a strongly minimal set and so is also strongly minimal. Essential continuity can either be shown directly or follows from the essential continuity of $(\mathbb{R}, 0)$.

What about the Prime Model?

The prime model may fail to have a non-compact connected component.

Counterexample

The set $\{\pm \log n : n \geq 1\}$ as a subspace of \mathbb{R} with the metric $\min\{|x - y|, 1\}$ is essentially continuous strongly minimal but has a totally disconnected prime model.

Proof.

The relevant set is actually definable in $(\mathbb{R}, 0)$, and so this is the theory of a non-compact definable subset of a strongly minimal set and so is also strongly minimal. Essential continuity can either be shown directly or follows from the essential continuity of $(\mathbb{R}, 0)$. □

Also an example showing that 'every definable set is either compact or co-pre-compact' is not good enough to be the definition of strongly minimal.

Groups

Fact (Reineke '75)

The strongly minimal groups are precisely the infinite characteristic p vector spaces and the infinite divisible Abelian groups in which for each prime p , there are finitely many elements of order p .

Fact (Reineke '75)

The strongly minimal groups are precisely the infinite characteristic p vector spaces and the infinite divisible Abelian groups in which for each prime p , there are finitely many elements of order p .

Divisible Abelian groups are known to be of the form

$$\mathbb{Q}^{\kappa} \oplus \bigoplus_p (\mathbb{Z}/p^{\infty}\mathbb{Z})^{\alpha_p},$$

Fact (Reineke '75)

The strongly minimal groups are precisely the infinite characteristic p vector spaces and the infinite divisible Abelian groups in which for each prime p , there are finitely many elements of order p .

Divisible Abelian groups are known to be of the form

$$\mathbb{Q}^{\kappa} \oplus \bigoplus_p (\mathbb{Z}/p^{\infty}\mathbb{Z})^{\alpha_p},$$

where $\mathbb{Z}/p^{\infty}\mathbb{Z}$ is the p -Prüfer group (i.e. the multiplicative group of p^n th roots of unity for fixed p and arbitrary n).

Fact (van Kampen '35)

If G is a locally compact Abelian (Hausdorff) topological group, then it has an open subgroup H topologically isomorphic to $\mathbb{R}^n \times K$ for some compact group K and some non-negative integer n .

Fact (van Kampen '35)

If G is a locally compact Abelian (Hausdorff) topological group, then it has an open subgroup H topologically isomorphic to $\mathbb{R}^n \times K$ for some compact group K and some non-negative integer n .

N.B.

- While G/H is a discrete group, it is not necessarily true that G is topologically isomorphic to $(G/H) \oplus H$.

Fact (van Kampen '35)

If G is a locally compact Abelian (Hausdorff) topological group, then it has an open subgroup H topologically isomorphic to $\mathbb{R}^n \times K$ for some compact group K and some non-negative integer n .

N.B.

- While G/H is a discrete group, it is not necessarily true that G is topologically isomorphic to $(G/H) \oplus H$.
- That said, G does always factor as $\mathbb{R}^n \oplus (G/\mathbb{R}^n)$.

Groups in Continuous Logic

- A group in continuous logic is some structure with some functions $(x, y) \mapsto x \cdot y$ and $x \mapsto x^{-1}$ and a constant e making it into an algebraic group.

Groups in Continuous Logic

- A group in continuous logic is some structure with some functions $(x, y) \mapsto x \cdot y$ and $x \mapsto x^{-1}$ and a constant e making it into an algebraic group. For a fixed signature this is an elementary class.

Groups in Continuous Logic

- A group in continuous logic is some structure with some functions $(x, y) \mapsto x \cdot y$ and $x \mapsto x^{-1}$ and a constant e making it into an algebraic group. For a fixed signature this is an elementary class.
- Note that we have smuggled some assumptions in. Not all metrizable topological groups admit *uniformly* continuous group operations.

Groups in Continuous Logic

- A group in continuous logic is some structure with some functions $(x, y) \mapsto x \cdot y$ and $x \mapsto x^{-1}$ and a constant e making it into an algebraic group. For a fixed signature this is an elementary class.
- Note that we have smuggled some assumptions in. Not all metrizable topological groups admit *uniformly* continuous group operations.
- (Ben Yaacov) There is a formula that defines a bi-invariant metric in any metric structure group.

Groups in Continuous Logic

- A group in continuous logic is some structure with some functions $(x, y) \mapsto x \cdot y$ and $x \mapsto x^{-1}$ and a constant e making it into an algebraic group. For a fixed signature this is an elementary class.
- Note that we have smuggled some assumptions in. Not all metrizable topological groups admit *uniformly* continuous group operations.
- (Ben Yaacov) There is a formula that defines a bi-invariant metric in any metric structure group.
- For any definable subgroup H the coset space G/H is an imaginary. If H is a normal subgroup, then G/H 's group operations are definable.

Groups in Continuous Logic

- A group in continuous logic is some structure with some functions $(x, y) \mapsto x \cdot y$ and $x \mapsto x^{-1}$ and a constant e making it into an algebraic group. For a fixed signature this is an elementary class.
- Note that we have smuggled some assumptions in. Not all metrizable topological groups admit *uniformly* continuous group operations.
- (Ben Yaacov) There is a formula that defines a bi-invariant metric in any metric structure group.
- For any definable subgroup H the coset space G/H is an imaginary. If H is a normal subgroup, then G/H 's group operations are definable. Note that compact subgroups are *always* definable with parameters.

Groups in Continuous Logic

- A group in continuous logic is some structure with some functions $(x, y) \mapsto x \cdot y$ and $x \mapsto x^{-1}$ and a constant e making it into an algebraic group. For a fixed signature this is an elementary class.
- Note that we have smuggled some assumptions in. Not all metrizable topological groups admit *uniformly* continuous group operations.
- (Ben Yaacov) There is a formula that defines a bi-invariant metric in any metric structure group.
- For any definable subgroup H the coset space G/H is an imaginary. If H is a normal subgroup, then G/H 's group operations are definable. Note that compact subgroups are *always* definable with parameters.
- (Ben Yaacov) Type-definable groups in ω -stable theories are definable.

Groups in Continuous Logic

- A group in continuous logic is some structure with some functions $(x, y) \mapsto x \cdot y$ and $x \mapsto x^{-1}$ and a constant e making it into an algebraic group. For a fixed signature this is an elementary class.
- Note that we have smuggled some assumptions in. Not all metrizable topological groups admit *uniformly* continuous group operations.
- (Ben Yaacov) There is a formula that defines a bi-invariant metric in any metric structure group.
- For any definable subgroup H the coset space G/H is an imaginary. If H is a normal subgroup, then G/H 's group operations are definable. Note that compact subgroups are *always* definable with parameters.
- (Ben Yaacov) Type-definable groups in ω -stable theories are definable.
- There is a superstable group with a type-definable subgroup that is not the intersection of definable subgroups:

Groups in Continuous Logic

- A group in continuous logic is some structure with some functions $(x, y) \mapsto x \cdot y$ and $x \mapsto x^{-1}$ and a constant e making it into an algebraic group. For a fixed signature this is an elementary class.
- Note that we have smuggled some assumptions in. Not all metrizable topological groups admit *uniformly* continuous group operations.
- (Ben Yaacov) There is a formula that defines a bi-invariant metric in any metric structure group.
- For any definable subgroup H the coset space G/H is an imaginary. If H is a normal subgroup, then G/H 's group operations are definable. Note that compact subgroups are *always* definable with parameters.
- (Ben Yaacov) Type-definable groups in ω -stable theories are definable.
- There is a superstable group with a type-definable subgroup that is not the intersection of definable subgroups: $\text{Th}(\mathbb{Q}, =, +, \cos, \sin)$. The subgroup $\{\cos(x) = 1, \sin(x) = 0\}$ is type-definable but not the intersection of definable subgroups. (Theory has no infinite definable proper subgroups.)

Theorem (H.)

A metrizable topological group G has a metric making it into a strongly minimal group if and only if it has a compact subgroup K such that G/K is topologically isomorphic to one of the following:

Theorem (H.)

A metrizable topological group G has a metric making it into a strongly minimal group if and only if it has a compact subgroup K such that G/K is topologically isomorphic to one of the following:

- An infinite characteristic p vector space.

Theorem (H.)

A metrizable topological group G has a metric making it into a strongly minimal group if and only if it has a compact subgroup K such that G/K is topologically isomorphic to one of the following:

- An infinite characteristic p vector space.
- $\mathbb{R}^n \oplus H$, where n is a non-negative integer and H is a divisible strongly minimal discrete group or possibly the trivial group (for $n > 0$).

Theorem (H.)

A metrizable topological group G has a metric making it into a strongly minimal group if and only if it has a compact subgroup K such that G/K is topologically isomorphic to one of the following:

- An infinite characteristic p vector space.
- $\mathbb{R}^n \oplus H$, where n is a non-negative integer and H is a divisible strongly minimal discrete group or possibly the trivial group (for $n > 0$).

In particular, G is essentially continuous if and only if it is of the second form with $n > 0$.

Theorem (H.)

A metrizable topological group G has a metric making it into a strongly minimal group if and only if it has a compact subgroup K such that G/K is topologically isomorphic to one of the following:

- An infinite characteristic p vector space.
- $\mathbb{R}^n \oplus H$, where n is a non-negative integer and H is a divisible strongly minimal discrete group or possibly the trivial group (for $n > 0$).

In particular, G is essentially continuous if and only if it is of the second form with $n > 0$.

G can fail to be a direct product of G/K and K . An easy example is the additive group of the p -adic numbers with the metric $\min\{|x - y|_p, 1\}$.

Strongly Minimal Groups in Continuous Logic II

- In a strongly minimal group a proper type-definable subgroup is always compact.

Strongly Minimal Groups in Continuous Logic II

- In a strongly minimal group a proper type-definable subgroup is always compact.
- If all elements of a group have 'compact order' and all non-identity elements are conjugate, then the group has size ≤ 2 .

Strongly Minimal Groups in Continuous Logic II

- In a strongly minimal group a proper type-definable subgroup is always compact.
- If all elements of a group have 'compact order' and all non-identity elements are conjugate, then the group has size ≤ 2 .
- From these: Strongly minimal groups are Abelian.

Strongly Minimal Groups in Continuous Logic II

- In a strongly minimal group a proper type-definable subgroup is always compact.
- If all elements of a group have 'compact order' and all non-identity elements are conjugate, then the group has size ≤ 2 .
- From these: Strongly minimal groups are Abelian.
- If some element fails to be divisible, then all elements must be order p for some prime p (because pG is a definable subgroup).

Strongly Minimal Groups in Continuous Logic II

- In a strongly minimal group a proper type-definable subgroup is always compact.
- If all elements of a group have 'compact order' and all non-identity elements are conjugate, then the group has size ≤ 2 .
- From these: Strongly minimal groups are Abelian.
- If some element fails to be divisible, then all elements must be order p for some prime p (because pG is a definable subgroup).
- If the group is divisible, then sets of order p elements must each be compact and therefore, by the classification of LCA groups, finite in G/K (where K is the compact subgroup).

Strongly Minimal Groups in Continuous Logic II

- In a strongly minimal group a proper type-definable subgroup is always compact.
- If all elements of a group have 'compact order' and all non-identity elements are conjugate, then the group has size ≤ 2 .
- From these: Strongly minimal groups are Abelian.
- If some element fails to be divisible, then all elements must be order p for some prime p (because pG is a definable subgroup).
- If the group is divisible, then sets of order p elements must each be compact and therefore, by the classification of LCA groups, finite in G/K (where K is the compact subgroup).
- Group has non-compact connected components iff it has a non-zero power of \mathbb{R} . (alternatively: if it has a non-zero power of \mathbb{R} , then the generic and therefore everything is divisible). □

Essential continuity seems to be a strong regularizing condition for strongly minimal groups, at least.

Essential continuity seems to be a strong regularizing condition for strongly minimal groups, at least.

Question

Are non-locally modular pregeometries even possible in essentially continuous strongly minimal sets?

Essential continuity seems to be a strong regularizing condition for strongly minimal groups, at least.

Question

Are non-locally modular pregeometries even possible in essentially continuous strongly minimal sets?

$(\mathbb{R}, +)$ and $(\mathbb{R}^2, +)$ cannot be extended to fields in the naïve way.

Essential continuity seems to be a strong regularizing condition for strongly minimal groups, at least.

Question

Are non-locally modular pregeometries even possible in essentially continuous strongly minimal sets?

$(\mathbb{R}, +)$ and $(\mathbb{R}^2, +)$ cannot be extended to fields in the naïve way.

Question

Can a Hrushovski construction or something similar build an essentially continuous strongly minimal set?

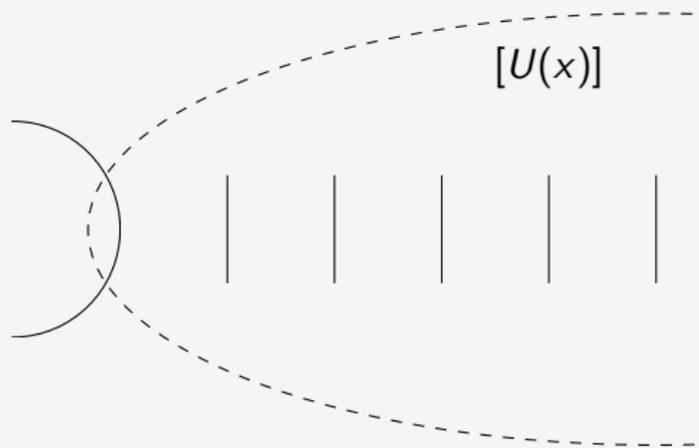
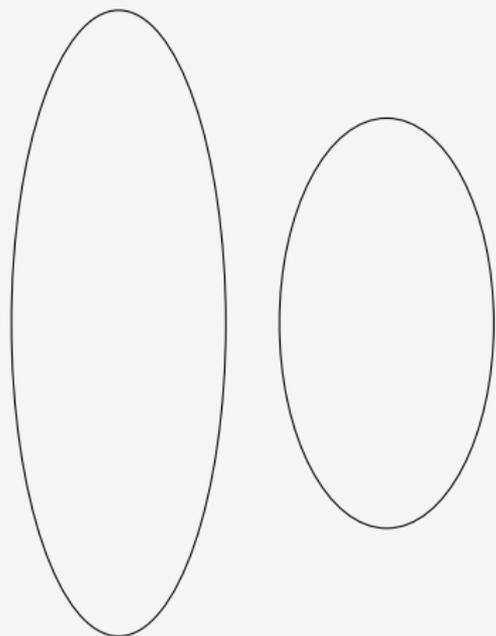
Thank you

Really the open set is:

$$U(x) := \forall y \left(\rho_n(x, y) < \frac{1}{3}(\varepsilon - \delta) \right) \vee \left(\rho_n(x, y) > \frac{2}{3}(\varepsilon - \delta) \right),$$

where $\forall x$ means 'there exists x in some elementary extension.'

Lies II



Proposition

Strongly Minimal Groups are Abelian.

- Lemma 1: Any type-definable proper subgroup in a strongly minimal group is compact.
- There must be some element g whose centralizer (subgroup of elements that commute with g), $C(g)$ is not all of the group. $C(g)$ is a zeroset, so by Lemma 1 point $C(g)$ is a compact subgroup. The orbit of g , $g^{\mathbb{Z}}$, is a subgroup of $C(g)$, so g has compact order.
- There is a natural bijection between $C(g) \backslash G$ (right coset space) and g^G (set of conjugates of g). This bijection is furthermore definable and uniformly bi-continuous.
- Not hard to show that since $C(g)$ is compact, $C(g) \backslash G$ must not be compact, implying that g^G is not compact.

Abelianity II

- Lemma 2: If all elements of a group have 'compact order' and all non-identity elements are approximately conjugate, then the group has no more than two elements.
- For any g, h not in the centralizer, g^G and h^G are definable,* non-compact sets, so they must overlap in sufficiently saturated models. Therefore they are equal, since they are conjugacy classes. This implies that they are conjugate in G/Z (where Z is the centralizer). They also must still have compact order in G/Z so we can apply Lemma 2, and we have that G/Z is finite, implying that G is compact. Contradiction. □